# RoHS RoHS-Compliant

# **Induction Motors**





## Features

## Optimal for Uni-Directional Continuous Operation

Induction motors are optimal for uni-directional continuous operation such as a conveyor system.

## ■Safety Standards and CE Marking

	1	-			
Standards	Certification Body	Standards File No.	CE Marking		
UL 1004 UL 2111	- UL	E64199 (1 W~6 W Type)			
CSA C22.2 No.100 CSA C22.2 No.77	OL.	E64197 (15 W~150 W Type)			
EN 60950-1 EN 60034-1 EN 60034-5 IEC 60664-1		Conform to EN/IEC Standards			
GB 12350	CQC	2005010401150786 (Single-Phase 1 W, 3 W Type) 2003010401091525 (Single-Phase 6 W Type) 2003010401091527 (Three-Phase 6 W Type) 2003010401091522 (Single-Phase 15 W~90 W Type) 2003010401091520 (Three-Phase 25 W~90 W Type) 2005010401150785 (2-Pole, High-Speed Type, Single-Phase 40 W~150 W Type) 2005010401150788 (2-Pole, High-Speed Type, Three-Phase 60 W~150 W Type)			

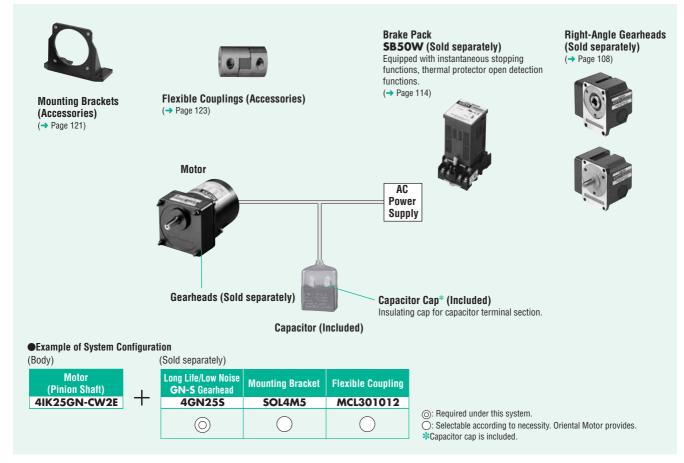
<sup>•</sup> When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

# 4IK25GN-UT4, 4IK25A-UT4, 5IK40GN-UT4, 5IK40A-UT4, 5IK60GE-UT4F, 5IK60A-UT4F, 5IK90GE-UT4F, 5IK90A-UT4F

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Standards	Certification Body	Standards File No.	CE Marking
EN 60950-1 EN 60034-1 EN 60034-5 IEC 60034-11	TÜV Rheinland	R50079501	Low Voltage Directives

The following products are not applicable to the table above.

## System Configuration



• The system configuration shown above is an example. Other configurations are available.

## Product Number Code

Motor

## 5 I K 40 GN - CW 2 T E

1	Motor Frame Size	0: 42 mm 2: 60 mm 3: 70 mm 4: 80 mm 5: 90 mm
2	Motor Type	I: Induction Motor
3	Series	K: K Series
4	Output Power (W)	(Example) <b>40</b> : 40 W
(5)	Motor Shaft Type	GN: GN Type Pinion Shaft GE: GE Type Pinion Shaft A: Round Shaft
6	Power Supply Voltage/ Number of Poles	AW: Single-Phase 100 VAC, 110/115 VAC 4-Pole         BW: Single-Phase 100 VAC, 110/115 VAC 2-Pole         CW: Single-Phase 200 VAC, 220/230 VAC 4-Pole           DW: Single-Phase 200 VAC, 220/230 VAC 2-Pole         SW: Three-Phase 200/220/230 VAC 4-Pole         TW: Three-Phase 200/220/230 VAC 2-Pole           U: Three-Phase 400 VAC 4-Pole         TW: Three-Phase 200/220/230 VAC 2-Pole
7	2, 3: RoHS-Compliant	
8	T, T4, T4F: Terminal Bo	x Type
9	Included Capacitor	J: For Single-Phase 100 VAC, 200 VAC U: For Single-Phase 110/115 VAC E: For Single-Phase 220/230 VAC Blank: Three-Phase Type

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

(Example) Model: 5IK40GN-CW2E → Motor nameplate and product approved under various safety standards: 5IK40GN-CW2

Gearhead

# 5 GN 50 S

1	Gearhead Frame Size	D: 42 mm <b>2</b> : 60 mm <b>3</b> : 70 mm <b>4</b> : 80 mm <b>5</b> : 90 mm					
2	Type of Pinion	GN: GN Type Pinion GE: GE Type Pinion					
3	Gear Ratio	Example) <b>50</b> : Gear Ratio of 1:50 <b>10X</b> denotes the decimal gearhead of gear ratio 1:10					
•	<b>GN</b> Type Pinion	S: Long Life/Low Noise GN-S Gearhead, RoHS-Compliant RH: Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant					
4	<b>GE</b> Type Pinion	S: Long Life GE-S Gearhead RH: Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant					

<sup>\*</sup>GN-K gearhead of frame size 42 mm complies to RoHS directive.

## ■General Specifications of Motors

## ●1 W, 3 W Type

Item	Specifications
Insulation Resistance	$100~M\Omega$ or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kV at 50 Hz or 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.
Temperature Rise	Temperature rise of windings are 75°C or less measured by the resistance change method after rated motor operation under normal ambient temperature and humidity, with connecting a gearhead or equivalent heat radiation plate*!.
Insulation Class	UL/CSA standards: Class A (105°C), EN standards: Class E (120°C)
Overheat Protection	Impedance protected
Ambient Temperature	-10°C~+40°C (nonfreezing)
Ambient Humidity	85% or less (noncondensing)
Degree of Protection	IP20

#### ●6 W~90 W Type, 2-Pole, High-Speed Type

Item	Specifications								
Insulation Resistance	$100 \text{ M}\Omega$ or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.								
Dielectric Strength	Sufficient to withstand 1.5 kV (three-phase 400 VAC: 2 kV) at 50 Hz and 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.								
Temperature Rise	Temperature rise of windings are 80°C or less measured by the resistance change method under normal ambient temperature and humidity, after rated motor operation with connecting a gearhead or equivalent heat radiation plate*1. (Three-phase type: 70°C or less)								
Insulation Class*2	Class B (130°C)								
Overheat Protection	6 W type has impedance protection.  All others have built-in thermal protector (automatic return type) Operating temperature; open: 130°C±5°C, close: 82°C±15°C								
Ambient Temperature	Single-phase 100 VAC, Single-phase 200 VAC, Three-phase 200 VAC: $-10^{\circ}\text{C} \sim +50^{\circ}\text{C}$ (nonfreezing) Other voltage: $-10^{\circ}\text{C} \sim +40^{\circ}\text{C}$ (nonfreezing)								
Ambient Humidity	85% or less (noncondensing)								
Degree of Protection	Lead Wire Type: IP20 Terminal Box Type: 6 W Type								

## \*1 Heat radiation plate (Material: Aluminum)

Motor Type	Size (mm)	Thickness (mm)
1 W, 3 W Type	80×80	
6 W Type	115×115	
15 W Type	125×125	5
25 W Type (2-Pole, High-Speed <b>4IK40</b> Type, <b>4IK60</b> Type)	135×135	5
40 W Type (2-Pole, High-Speed <b>5IK60</b> Type)	165×165	
60 W, 90 W, 150 W Type	200×200	

<sup>\*2</sup> The following products are recognized as class E (120°C).

4IK25GN-UT4, 4IK25A-UT4, 5IK40GN-UT4, 5IK40A-UT4, 5IK60GE-UT4F, 5IK60A-UT4F, 5IK90GE-UT4F, 5IK90A-UT4F

RoHS Induction Motors 1 W / 3 W

Frame Size: **□42** mm



(Gearhead sold separately)

## ■Specifications - Continuous Rating (RoHS)

<b>SU</b> us	(M)	C	$\epsilon$
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Mode Lead Wire		Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor	
Pinion Shaft Type	Round Shaft Type	W	VAC	Hz	Α	mN·m	mN·m	r/min	μF	
(ZP) OIK1GN-AW2J	OIK1A-AW2J	1	Single-Phase 100	50	0.107	- 8	9.5	1000	1.5	
ZP VIKTON-AWZJ	OIK I A-AVV 23	'	Sillyle-Filase 100	60	0.102	0	8	1200	1.5	
(ZP) OIK1GN-AW3U	0IK1A-AW3U	1	Single-Phase 110	60	0.074		8	1200	1.0	
ZP UIKTGIN-AVV3U		'	Single-Phase 115	00	0.078	8	0	1200	1.0	
(ZP) OIK1GN-CW2J	OIK1A-CW2J	0.8	Single-Phase 200	50	0.057	7	8	1000	0.35	
ZP UIKTGIN-CWZJ		1	Siligie-Pliase 200	60	0.055	,	0	1200	0.35	
(ZP) OIK3GN-BW2J	OIK3A-BW2J	3	Cinala Dhana 100	50	0.109	6	12	2400	1.8	
ZP UIKSGIN-BWZJ	UIK3A-BW2J	3	Single-Phase 100	60	0.123	0	10	3000	1.0	
(ZP) OIK3GN-BW3U	OINS V BANSII	2	Single-Phase 110	60	0.115		10	3000	1.5	
ZP UIK3GN-BW3U	OIK3A-BW3U	3	Single-Phase 115	00	0.118	6	10	3000	1.5	
(ZP) OIK3GN-DW2J	OIK3A-DW2J	2.5	Single-Phase 200	50	0.057	- 5	9.5	2500	0.45	
ZP UIKSUN-DWZJ	UINSA-DW ZJ	3	Sillyle-FildSe 200	60	0.064	3	9.0	3100	0.43	

<sup>•</sup> The J and U at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.
When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

## Product Line

## ● Motor (RoHS)

Туре	Model								
	Pinion Shaft Type	Round Shaft Type							
	0IK1GN-AW2J	0IK1A-AW2J							
	0IK1GN-AW3U	0IK1A-AW3U							
Lead Wire	0IK1GN-CW2J	0IK1A-CW2J							
Leau wire	0IK3GN-BW2J	0IK3A-BW2J							
	0IK3GN-BW3U	OIK3A-BW3U							
	0IK3GN-DW2J	0IK3A-DW2J							

## ● Gearhead (Sold Separately) RoHS

Туре	Gearhead Model	Gear Ratio
Parallel Shaft	0GN□K	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>■</sup> Enter the gear ratio in the box (□) within the model name.

**ZP**: Impedance protected

## ■Gearmotor – Torque Table

•Gearheads are sold separately. Decimal gearheads are not available.

■Enter the gear ratio in the box (□) within the model name.

•A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (4-pole type; 50 Hz: 1500 r/min, 60 Hz: 1800 r/min, 2-pole type; 50 Hz: 3000 r/min, 60 Hz: 3600 r/min) by the gear ratio. The actual speed is 2 - 33% less than the displayed value, depending on the size of the load.

																			Uni	t = N•m
Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
/ OGN□K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1
/ ogn□k	0.019	0.023	0.032	0.039	0.049	0.058	0.073	0.088	0.11	0.13	0.16	0.19	0.26	0.32	0.35	0.42	0.47	0.57	0.71	0.85
																			Uni	t = N•n
Speed r/min	1000	833	600	500	400	333	240	200	166	120	100	83	60	50	40	33	30	25	20	16
Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
/ OGN□K	0.029	0.035	0.049	0.058	0.073	0.087	0.11	0.13	0.16	0.2	0.24	0.29	0.4	0.48	0.53	0.64	0.71	0.85	1	1
/ OGN□K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1
																			Uni	t = N·n
Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
OGNUK	0.019	0.023	0.032	0.039	0.049	0.058	0.073	0.088	0.11	0.13	0.16	0.19	0.26	0.32	0.35	0.42	0.47	0.57	0.71	0.85
																			Uni	t = N·m
Speed r/min	1200	1000	720	600	480	400	288	240	200	144	120	100	72	60	48	40	36	30	24	20
Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
/ OGN□K	0.024	0.029	0.041	0.049	0.061	0.073	0.091	0.11	0.13	0.17	0.2	0.24	0.33	0.4	0.44	0.53	0.59	0.71	0.89	1
/ OGN□K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1
	r/min Gear Ratio  / OGN K / OGN K  Speed r/min Gear Ratio  / OGN K  Gear Ratio  / OGN K  Speed r/min Gear Ratio  / OGN K  OGN K  OGN K  OGN K  OGN K	r/min   S00     Gear Ratio   3     OGN   K   0.023     OGN   K   0.019     Speed r/min   1000     Gear Ratio   3     OGN   K   0.029     OGN   K   0.023     Speed r/min   600     Gear Ratio   3     OGN   K   0.019     Speed r/min   1200     Gear Ratio   3     OGN   K   0.024	r/min	r/min         500         416         300           Gear Ratio         3         3.6         5           / OGN□K         0.023         0.028         0.038           / OGN□K         0.019         0.023         0.032           Speed r/min         1000         833         600           Gear Ratio         3         3.6         5           / OGN□K         0.029         0.035         0.049           / OGN□K         0.023         0.028         0.038           Speed r/min         600         500         360           Gear Ratio         3         3.6         5           / OGN□K         0.019         0.023         0.032           Speed r/min         1200         1000         720           Gear Ratio         3         3.6         5           / OGN□K         0.024         0.029         0.041	r/min         500         416         300         250           Gear Ratio         3         3.6         5         6           OGN□K         0.023         0.028         0.038         0.046           OGN□K         0.019         0.023         0.032         0.039           Speed r/min         1000         833         600         500           Gear Ratio         3         3.6         5         6           OGN□K         0.029         0.035         0.049         0.058           OGN□K         0.023         0.028         0.038         0.046           Speed r/min         600         500         360         300           Gear Ratio         3         3.6         5         6           OGN□K         0.019         0.023         0.032         0.039           Speed r/min         1200         1000         720         600           Gear Ratio         3         3.6         5         6           OGN□K         0.024         0.029         0.041         0.049	r/min	r/min         500         416         300         250         200         166           Gear Ratio         3         3.6         5         6         7.5         9           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069           / OGN□K         0.019         0.023         0.032         0.039         0.049         0.058           Speed r/min         1000         833         600         500         400         333           Gear Ratio         3         3.6         5         6         7.5         9           / OGN□K         0.029         0.035         0.049         0.058         0.073         0.087           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069           Speed r/min         600         500         360         300         240         200           Gear Ratio         3         3.6         5         6         7.5         9           / OGN□K         0.019         0.023         0.032         0.032         0.039         0.049         0.058           Speed r/min         1200         1000         720<	r/min         500         416         300         250         200         166         120           Gear Ratio         3         3.6         5         6         7.5         9         12.5           OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087           OGN□K         0.019         0.023         0.032         0.039         0.049         0.058         0.073           Speed r/min         1000         833         600         500         400         333         240           OGN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11           OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087           Speed r/min         600         500         360         300         240         200         144           Gear Ratio         3         3.6         5         6         7.5         9         12.5           OGN□K         0.019         0.023         0.032         0.039         0.049         0.058         0.073           OGN□K         0.019         0.023 <td>r/min         500         416         300         250         200         166         120         100           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15           OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1           OGN□K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088           Speed r/min         1000         833         600         500         400         333         240         200           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15           OGN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13           OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1           Speed r/min         600         500         360         300         240         200         144         120           OGN□K         0.019         0.023         <t< td=""><td>r/min         500         416         300         250         200         166         120         100         83           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18           OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12           OGN□K         0.019         0.023         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11           Speed r/min         1000         833         600         500         400         333         240         200         166           JogN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13         0.16           JogN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12           Speed r/min         600         500         360         300         240         200         144         120         100           Gear Ra</td><td>r/min         500         416         300         250         200         166         120         100         83         60           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25           / OGN K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16           / OGN K         0.019         0.023         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13           / OGN K         0.029         0.035         0.049         0.058         0.073         0.087         0.1         0.13         0.16         0.2           OGN K         0.029         0.035         0.049         0.058         0.073         0.087         0.1         0.12         0.16           Speed r/min         600         500         360         300         240         200         144         120         100         72           OGN K         0.019         0.023         0.032         0.032         0.039</td><td>r/min         500         416         300         250         200         166         120         100         83         60         50           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30           / OGN   K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19           / OGN   K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16           Speed r/min         1000         833         600         500         400         333         240         200         166         120         100           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30           OGN   K         0.029         0.035         0.049         0.058         0.073         0.087         0.1         0.12         0.16         0.19           Speed r/min         600         500         360</td><td>r/min         500         416         300         250         200         166         120         100         83         60         50         41           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23           / OGN□K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23           Speed r/min         1000         833         600         500         400         333         240         200         166         120         100         83           / OGN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13         0.16         0.2         0.24         0.29           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087</td><td>r/min         500         416         300         250         200         166         120         100         83         60         50         41         30           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23         0.31           / OGN□K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23           Speed r/min         1000         833         600         500         400         333         240         200         166         120         100         83         60           / OGN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13         0.16         0.2         0.24         0.29         0.4           / OGN□K         0.023         0.023         0.038&lt;</td><td>  F/min   Sub   416   Sub   250   200   166   120   100   83   60   50   41   30   25    </td><td>r/min         500         416         300         250         200         166         120         100         83         60         50         41         30         25         20           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75           OGN K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23         0.31         0.38         0.42           OGN K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23         0.31         0.35           Speed fr/min         1000         833         600         500         400         333         240         200         166         120         100         83         60         50         40           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         <t< td=""><td>r/min         SUO         416         300         250         200         166         120         100         83         60         50         41         30         25         20         16           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75         90           / OGN K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.16         0.19         0.23         0.31         0.38         0.42         0.5           OGN K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23         0.32         0.35         0.42           Speed fr/min         1000         833         600         500         400         333         240         200         166         120         100         83         60         50         40         33           Gear Ratio         3         3.6         5         6         7.5</td><td>  Speed   1000   833   600   500   400   333   240   200   166   120   100   83   60   50   41   30   25   20   16   15    </td><td>  Fr/min   Suu   416   300   250   200   166   120   100   83   60   50   41   30   25   20   16   15   12.5    </td><td>Speed r/min         500         416         300         250         200         166         120         100         83         60         50         41         30         25         20         16         15         12.5         10           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75         90         100         120         150           / OGNIIK         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23         0.31         0.32         0.35         0.42         0.57         0.71         0.84           / OGNIIK         0.019         0.023         0.032         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.26         0.32         0.32         0.42         0.57         0.71         0.71           Unit         Speed r/min         1000         833         600         50         40         33         30</td></t<></td></t<></td>	r/min         500         416         300         250         200         166         120         100           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15           OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1           OGN□K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088           Speed r/min         1000         833         600         500         400         333         240         200           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15           OGN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13           OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1           Speed r/min         600         500         360         300         240         200         144         120           OGN□K         0.019         0.023 <t< td=""><td>r/min         500         416         300         250         200         166         120         100         83           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18           OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12           OGN□K         0.019         0.023         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11           Speed r/min         1000         833         600         500         400         333         240         200         166           JogN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13         0.16           JogN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12           Speed r/min         600         500         360         300         240         200         144         120         100           Gear Ra</td><td>r/min         500         416         300         250         200         166         120         100         83         60           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25           / OGN K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16           / OGN K         0.019         0.023         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13           / OGN K         0.029         0.035         0.049         0.058         0.073         0.087         0.1         0.13         0.16         0.2           OGN K         0.029         0.035         0.049         0.058         0.073         0.087         0.1         0.12         0.16           Speed r/min         600         500         360         300         240         200         144         120         100         72           OGN K         0.019         0.023         0.032         0.032         0.039</td><td>r/min         500         416         300         250         200         166         120         100         83         60         50           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30           / OGN   K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19           / OGN   K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16           Speed r/min         1000         833         600         500         400         333         240         200         166         120         100           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30           OGN   K         0.029         0.035         0.049         0.058         0.073         0.087         0.1         0.12         0.16         0.19           Speed r/min         600         500         360</td><td>r/min         500         416         300         250         200         166         120         100         83         60         50         41           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23           / OGN□K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23           Speed r/min         1000         833         600         500         400         333         240         200         166         120         100         83           / OGN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13         0.16         0.2         0.24         0.29           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087</td><td>r/min         500         416         300         250         200         166         120         100         83         60         50         41         30           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23         0.31           / OGN□K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23           Speed r/min         1000         833         600         500         400         333         240         200         166         120         100         83         60           / OGN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13         0.16         0.2         0.24         0.29         0.4           / OGN□K         0.023         0.023         0.038&lt;</td><td>  F/min   Sub   416   Sub   250   200   166   120   100   83   60   50   41   30   25    </td><td>r/min         500         416         300         250         200         166         120         100         83         60         50         41         30         25         20           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75           OGN K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23         0.31         0.38         0.42           OGN K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23         0.31         0.35           Speed fr/min         1000         833         600         500         400         333         240         200         166         120         100         83         60         50         40           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         <t< td=""><td>r/min         SUO         416         300         250         200         166         120         100         83         60         50         41         30         25         20         16           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75         90           / OGN K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.16         0.19         0.23         0.31         0.38         0.42         0.5           OGN K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23         0.32         0.35         0.42           Speed fr/min         1000         833         600         500         400         333         240         200         166         120         100         83         60         50         40         33           Gear Ratio         3         3.6         5         6         7.5</td><td>  Speed   1000   833   600   500   400   333   240   200   166   120   100   83   60   50   41   30   25   20   16   15    </td><td>  Fr/min   Suu   416   300   250   200   166   120   100   83   60   50   41   30   25   20   16   15   12.5    </td><td>Speed r/min         500         416         300         250         200         166         120         100         83         60         50         41         30         25         20         16         15         12.5         10           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75         90         100         120         150           / OGNIIK         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23         0.31         0.32         0.35         0.42         0.57         0.71         0.84           / OGNIIK         0.019         0.023         0.032         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.26         0.32         0.32         0.42         0.57         0.71         0.71           Unit         Speed r/min         1000         833         600         50         40         33         30</td></t<></td></t<>	r/min         500         416         300         250         200         166         120         100         83           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18           OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12           OGN□K         0.019         0.023         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11           Speed r/min         1000         833         600         500         400         333         240         200         166           JogN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13         0.16           JogN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12           Speed r/min         600         500         360         300         240         200         144         120         100           Gear Ra	r/min         500         416         300         250         200         166         120         100         83         60           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25           / OGN K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16           / OGN K         0.019         0.023         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13           / OGN K         0.029         0.035         0.049         0.058         0.073         0.087         0.1         0.13         0.16         0.2           OGN K         0.029         0.035         0.049         0.058         0.073         0.087         0.1         0.12         0.16           Speed r/min         600         500         360         300         240         200         144         120         100         72           OGN K         0.019         0.023         0.032         0.032         0.039	r/min         500         416         300         250         200         166         120         100         83         60         50           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30           / OGN   K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19           / OGN   K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16           Speed r/min         1000         833         600         500         400         333         240         200         166         120         100           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30           OGN   K         0.029         0.035         0.049         0.058         0.073         0.087         0.1         0.12         0.16         0.19           Speed r/min         600         500         360	r/min         500         416         300         250         200         166         120         100         83         60         50         41           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23           / OGN□K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23           Speed r/min         1000         833         600         500         400         333         240         200         166         120         100         83           / OGN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13         0.16         0.2         0.24         0.29           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087	r/min         500         416         300         250         200         166         120         100         83         60         50         41         30           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50           / OGN□K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23         0.31           / OGN□K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23           Speed r/min         1000         833         600         500         400         333         240         200         166         120         100         83         60           / OGN□K         0.029         0.035         0.049         0.058         0.073         0.087         0.11         0.13         0.16         0.2         0.24         0.29         0.4           / OGN□K         0.023         0.023         0.038<	F/min   Sub   416   Sub   250   200   166   120   100   83   60   50   41   30   25	r/min         500         416         300         250         200         166         120         100         83         60         50         41         30         25         20           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75           OGN K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23         0.31         0.38         0.42           OGN K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23         0.31         0.35           Speed fr/min         1000         833         600         500         400         333         240         200         166         120         100         83         60         50         40           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18 <t< td=""><td>r/min         SUO         416         300         250         200         166         120         100         83         60         50         41         30         25         20         16           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75         90           / OGN K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.16         0.19         0.23         0.31         0.38         0.42         0.5           OGN K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23         0.32         0.35         0.42           Speed fr/min         1000         833         600         500         400         333         240         200         166         120         100         83         60         50         40         33           Gear Ratio         3         3.6         5         6         7.5</td><td>  Speed   1000   833   600   500   400   333   240   200   166   120   100   83   60   50   41   30   25   20   16   15    </td><td>  Fr/min   Suu   416   300   250   200   166   120   100   83   60   50   41   30   25   20   16   15   12.5    </td><td>Speed r/min         500         416         300         250         200         166         120         100         83         60         50         41         30         25         20         16         15         12.5         10           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75         90         100         120         150           / OGNIIK         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23         0.31         0.32         0.35         0.42         0.57         0.71         0.84           / OGNIIK         0.019         0.023         0.032         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.26         0.32         0.32         0.42         0.57         0.71         0.71           Unit         Speed r/min         1000         833         600         50         40         33         30</td></t<>	r/min         SUO         416         300         250         200         166         120         100         83         60         50         41         30         25         20         16           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75         90           / OGN K         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.16         0.19         0.23         0.31         0.38         0.42         0.5           OGN K         0.019         0.023         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.23         0.32         0.35         0.42           Speed fr/min         1000         833         600         500         400         333         240         200         166         120         100         83         60         50         40         33           Gear Ratio         3         3.6         5         6         7.5	Speed   1000   833   600   500   400   333   240   200   166   120   100   83   60   50   41   30   25   20   16   15	Fr/min   Suu   416   300   250   200   166   120   100   83   60   50   41   30   25   20   16   15   12.5	Speed r/min         500         416         300         250         200         166         120         100         83         60         50         41         30         25         20         16         15         12.5         10           Gear Ratio         3         3.6         5         6         7.5         9         12.5         15         18         25         30         36         50         60         75         90         100         120         150           / OGNIIK         0.023         0.028         0.038         0.046         0.058         0.069         0.087         0.1         0.12         0.16         0.19         0.23         0.31         0.32         0.35         0.42         0.57         0.71         0.84           / OGNIIK         0.019         0.023         0.032         0.032         0.039         0.049         0.058         0.073         0.088         0.11         0.13         0.16         0.19         0.26         0.32         0.32         0.42         0.57         0.71         0.71           Unit         Speed r/min         1000         833         600         50         40         33         30

## ■Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

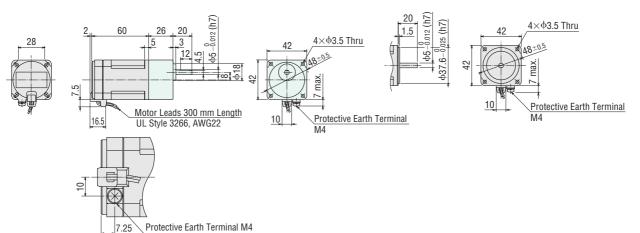
→ Page 107

## ■ Dimensions (Unit = mm)

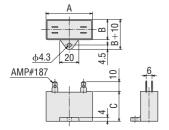
Mounting screws are included with gearheads.

## ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



## 

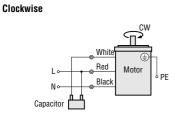


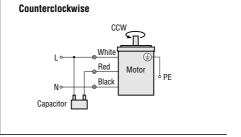
<u> </u>	` '						
Mo	odel	Capacitor	۸	В	С	Mass	Capacitor
Pinion Shaft Type	Round Shaft Type	Model	Α	Ь	U	(g)	Cap
0IK1GN-AW2J	0IK1A-AW2J	CH15FAUL	31	14.5	23.5	18	
0IK1GN-AW3U	OIK1A-AW3U	CH10FAUL	31	14.5	23.5	18	
0IK1GN-CW2J	0IK1A-CW2J	CH035BFAUL	31	17	27	24	Included
0IK3GN-BW2J	OIK3A-BW2J	CH18FAUL	31	14.5	23.5	18	Illiciuueu
0IK3GN-BW3U	OIK3A-BW3U	CH15FAUL	31	14.5	23.5	18	
0IK3GN-DW2J	0IK3A-DW2J	CH045BFAUL	31	17	27	24	

## **■**Connection Diagrams

- •The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.

## OIK1GN-AW2J, OIK1GN-AW3U, OIK1GN-CW2J OIK3GN-BW2J, OIK3GN-BW3U, OIK3GN-DW2J





PE: Protective Earth

#### Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

RoHS Induction Motors

6 W

Frame Size: **□60** mm





(Gearhead sold separately)

## ■Specifications – Continuous Rating RoHS

<b>S</b> Us	( <u>m</u> )	Œ	
US		-	

	<u> </u>			, J <u>J </u>					· · · · · · · · · · · · · · · · · · ·	15 🔾
	Mode Upper Model Name: F Lower Model Name ():	Pinion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	А	mN∙m	mN•m	r/min	μF
<b>ZP</b>	2IK6GN-AW2J	2IK6GN-AW2TJ	6	Single-Phase 100	50	0.199	45	49	1200	3.5
ZP	(2IK6A-AW2J)	(2IK6A-AW2TJ)	0	Sillyle-Filase 100	60	0.217	40	41	1450	3.0
ZP)	2IK6GN-AW2U	2IK6GN-AW2TU	6	Single-Phase 110	60	0.178	40	41	1450	2.5
ZP	(2IK6A-AW2U)	(2IK6A-AW2TU)	0	Single-Phase 115	00	0.182	40	41	1430	2.0
ZP)	2IK6GN-CW2J	2IK6GN-CW2TJ	6 Single-Phase 200	50	0.100	45	49	1150	0.8	
ZP	(2IK6A-CW2J)	(2IK6A-CW2TJ)	0	Siligle-Pilase 200	60	0.103	40	41	1450	0.0
				Single-Phase 220	50	0.103	38	49	1150	
(ZD)	2IK6GN-CW2E	2IK6GN-CW2TE	6	Sillyle-Filase 220	60	0.091	40	41	1450	0.6
<b>ZP</b>	(2IK6A-CW2E)	(2IK6A-CW2TE)	0	Cinala Dhaga 220	50	0.107	45	49	1200	0.0
				Single-Phase 230	60	0.094	40	41	1450	
				Three-Phase 200	50	0.081	49	49	1200	
70	7B)	2IK6GN-SW2T		Tillee-Phase 200	60	0.072	41	41	1400	
4		(2IK6A-SW2T)	6	Three-Phase 220	60	0.076	41	41	1500	1 -
				Three-Phase 230	60	0.079	41	41	1500	

The **J**, **U** and **E** at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

## Product Line

## ● Motor (RoHS)

Tuno	N	/lodel
Type	Pinion Shaft Type	Round Shaft Type
	2IK6GN-AW2J	2IK6A-AW2J
Lead Wire	2IK6GN-AW2U	2IK6A-AW2U
	2IK6GN-CW2J	2IK6A-CW2J
	2IK6GN-CW2E	2IK6A-CW2E
	2IK6GN-SW2	2IK6A-SW2
	2IK6GN-AW2TJ	2IK6A-AW2TJ
	2IK6GN-AW2TU	2IK6A-AW2TU
Terminal Box	2IK6GN-CW2TJ	2IK6A-CW2TJ
	2IK6GN-CW2TE	2IK6A-CW2TE
	2IK6GN-SW2T	2IK6A-SW2T

## Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	2GN□5	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	2GN10XS (Decima	al gearhead)

● Enter the gear ratio in the box (□) within the model name.

**ZP**: Impedance protected

## ■Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 3 N·m.

<>50 HZ																				Uni	t = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2IK6GN-AW2 J 2IK6GN-CW2 J 2IK6GN-CW2 E 2IK6GN-SW2 /	<b>2GN</b> □S	0.12	0.14	0.20	0.24	0.30	0.36	0.50	0.60	0.71	0.89	1.1	1.3	1.6	1.9	2.4	2.9	3	3	3	3

<b>♦60 Hz</b>																				Uni	t = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2IK6GN-AW2 2IK6GN-AW2 U 2IK6GN-CW2 J 2IK6GN-CW2 E 2IK6GN-SW2	<b>2GN</b> □S	0.10	0.12	0.17	0.20	0.25	0.30	0.42	0.50	0.60	0.75	0.90	1.1	1.4	1.6	2.0	2.4	2.7	3	3	3

## Permissible Overhung Load and Permissible Thrust Load

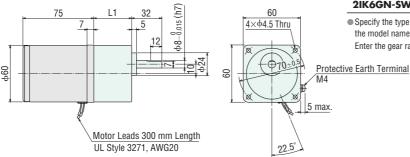
Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

→ Page 107

## **Dimensions** (Unit = mm)

Mounting screws are included with gearheads.



Motor Model	Gearhead Model	Gear Ratio	L1
2IK6GN-AW2□ 2IK6GN-CW2□	2GN□S	3~18	30
2IK6GN-SW2	ZGN_3	<b>25</b> ~180	40

lacksquare Specify the type of the capacitor to be included by entering  ${f J}, {f U}$  or  ${f E}$  in the box ( ${lacksquare}$ ) within the model name.

Enter the gear ratio in the box ( $\square$ ) within the model name.



Detail Drawing of Protective Earth Terminal

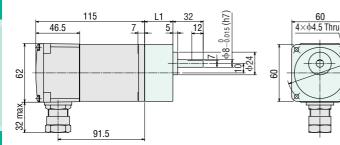
#### 

Mass: Motor 0.9 kg Gearhead 0.4 kg

Motor Model	Gearhead Model	Gear Ratio	L1
2IK6GN-AW2T	2GN□S	3~18	30
2IK6GN-CW2I	2GN□5	<b>25</b> ~180	40

lacksquare Specify the type of the capacitor to be included by entering f J, U or f E in the box (lacksquare) within the model name.

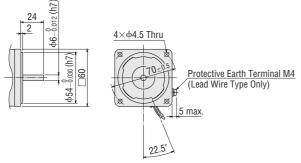
Enter the gear ratio in the box  $(\Box)$  within the model name.



 $\bullet$  Use cable with a diameter of  $\varphi 8 \sim \varphi 12$  mm.

## ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

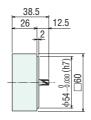


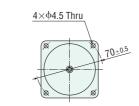
## 

Can be connected to **GN** pinion shaft type.

## **2GN10XS**

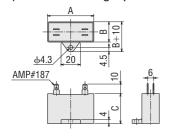
Mass: 0.2 kg





## ♦Capacitor

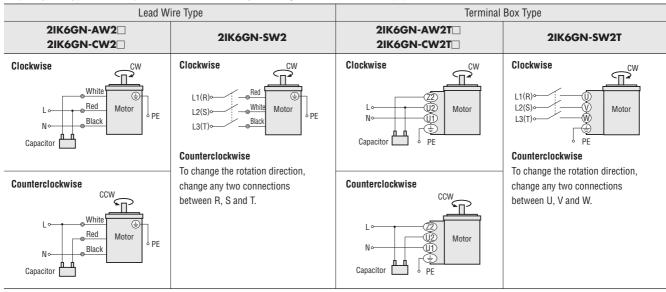
(Included with single-phase motors)



Upper Model Name	del e: Pinion Shaft Type ( ): Round Shaft Type	Capacitor Model	А	В	С	Mass (g)	Capacitor Cap
Lead Wire Type	Terminal Box Type						
2IK6GN-AW2J (2IK6A-AW2J)	2IK6GN-AW2TJ (2IK6A-AW2TJ)	CH35FAUL2	31	17	27	25	
2IK6GN-AW2U (2IK6A-AW2U)	2IK6GN-AW2TU (2IK6A-AW2TU)	CH25FAUL2	31	17	27	25	Included
2IK6GN-CW2J (2IK6A-CW2J)	2IK6GN-CW2TJ (2IK6A-CW2TJ)	CH08BFAUL	31	17	27	20	Iliciuded
2IK6GN-CW2E (2IK6A-CW2E)	2IK6GN-CW2TE (2IK6A-CW2TE)	CH06BFAUL	31	14.5	23.5	15	

## **■**Connection Diagrams

- •The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

RoHS Induction Motors 15 W

Frame Size: **□70** mm



(Gearhead sold separately)

## ■Specifications - Continuous Rating (RoHS)

<b>Al</b> us	(m)	C	$\epsilon$
<b>1 1 1 1 1 1 1 1 1 1</b>		•	•

			_							
Model Lead Wire		Output Power Voltage		Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor	
Pinion Shaft Type	Round Shaft Type	W	VAC	Hz	Α	mN·m	mN·m	r/min	μF	
TP 3IK15GN-AW2J	3IK15A-AW2J	15	Single-Phase 100	50	0.36	80	125	1200	5.5	
JP SIKTSOIT-AW25	JIK I JA-AWZJ	13	Siligie-Filase 100	60	0.37	65	105	1450	3.3	
TP) 3IK15GN-AW2U	3IK15A-AW2U	15	Single-Phase 110	60	0.33	- 65	105	1450	4.5	
JP SIKTSGN-AW20	SIK I SA-AW 20	10	Single-Phase 115	00	0.34		103	1430	4.0	
TP 3IK15GN-CW2J	3IK15A-CW2J	15	Single-Phase 200	50	0.18	80	125	1200	1.5	
IP SIK I SOIN-CW23	SIK I SA-CW23	13	Siligie-Filase 200	60	0.19	65	105	1450	1.0	
			Single-Phase 220	50	0.19	70	125	1200		
TD 21V1ECN_CW2E	3IK15GN-CW2E 3IK15A-CW2E 15	15	Sillyle-Filase 220	60	0.16	65	105	1450	1.0	
TP 3IK15GN-CW2E		13	Single-Phase 230	50	0.19	75	125	1200	1.0	
			Sillyle-FildSe 230	60	0.16	65	105	1450		

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

## Product Line

## ● Motor (RoHS)

Tuno	Mo	del
Type	Pinion Shaft Type	Round Shaft Type
	3IK15GN-AW2J	3IK15A-AW2J
Lead Wire	3IK15GN-AW2U	3IK15A-AW2U
Leau Wire	3IK15GN-CW2J	3IK15A-CW2J
	3IK15GN-CW2E	3IK15A-CW2E

## ● Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	3GN□5	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	3GN10XS (Decima	al gearhead)

● Enter the gear ratio in the box (□) within the model name.

<sup>(</sup>TP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

## ■Gearmotor – Torque Table

- Gearheads and decimal gearheads are sold separately.
- ●Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 5 N·m.

♦ 50 Hz Unit = N															t = N•m						
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3IK15GN-AW2J 3IK15GN-CW2J 3IK15GN-CW2E	/ 3GN□S	0.30	0.36	0.51	0.61	0.76	0.91	1.3	1.5	1.8	2.3	2.7	3.3	4.1	5	5	5	5	5	5	5

♦ 60 Hz															it = N•m						
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3IK15GN-AW2J 3IK15GN-AW2U 3IK15GN-CW2J 3IK15GN-CW2E	<b>3GN</b> □S	0.26	0.31	0.43	0.51	0.64	0.77	1.1	1.3	1.5	1.9	2.3	2.8	3.5	4.2	5	5	5	5	5	5

Motor Model

3IK15GN-AW2

3IK15GN-CW2

Gearhead Model

3GN<sub>□</sub>S

## Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

→ Page 107

## Dimensions (Unit = mm)

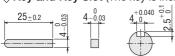
Mounting screws are included with gearheads.

#### 

Mass: Motor 1.1 kg Gearhead 0.55 kg

<u> </u>	80 L1 32 5	70 t	Specify the type of the capacitor to be included by entering <b>J</b> , <b>U</b> or <b>E</b> in the box ( <b>(</b> ) within the model name.  Inter the gear ratio in the box ( <b>(</b> ) within the model name.
69ф	Motor Leads 300 mm Length UL Style 3271, AWG20	82±0.5 Protectiv M4 5 max.	Protective Earth Terminal  Potail Drawing of Protective Earth Terminal

 $\diamondsuit$  Key and Key Slot (The key is included with the gearhead)



Detail Drawing of Protective Earth Terminal

Gear Ratio

3~18

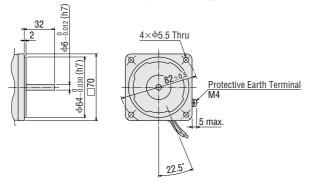
**25~180** 

L1

32

## ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

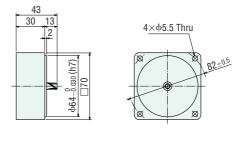


## 

Can be connected to **GN** pinion shaft type.

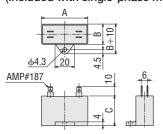
#### **3GN10XS**

Mass: 0.3 kg



## $\Diamond$ Capacitor

(Included with single-phase motors)

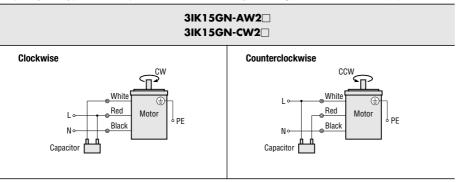


## 

Pinion Shaft Type	del Round Shaft Type	Capacitor Model	Α	В	С	Mass (g)	Capacitor Cap
3IK15GN-AW2J	3IK15A-AW2J	CH55FAUL2	38	21	31	40	
3IK15GN-AW2U	3IK15A-AW2U	CH45FAUL2	37	18	27	30	Included
3IK15GN-CW2J	3IK15A-CW2J	CH15BFAUL	38	21	31	35	Illciuueu
3IK15GN-CW2E	3IK15A-CW2E	CH10BFAUL	37	18	27	30	

## Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- •Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within the model name.



PE: Protective Earth

Note

 $Change \ the \ direction \ of \ single-phase \ motor \ rotation \ only \ after \ bringing \ the \ motor \ to \ a \ stop.$ 

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

**Induction Motors** 

# 25 W

Frame Size: 

■80 mm





(Gearhead sold separately)

Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## ■Specifications – Continuous Rating (RoHS)

<b>CAL</b> US	<b>(W</b> )	(
---------------	-------------	---

	•			• •				\$2 <b>—</b> 88 © <b>11</b>						
	Model Upper Model Name: P Lower Model Name ( ):	inion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor				
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	A	mN∙m	mN∙m	r/min	μF				
(TP)	4IK25GN-AW2J	4IK25GN-AW2TJ	25	Cingle Dhose 100	50	0.51	130	205	1200	8.0				
	(4IK25A-AW2J)	(4IK25A-AW2TJ)	20	Single-Phase 100	60	0.52	120	170	1450	6.0				
(TP)	4IK25GN-AW2U	4IK25GN-AW2TU	25	Single-Phase 110	60	0.46	120	170	1450	6.5				
	(4IK25A-AW2U)	(4IK25A-AW2TU)	20	Single-Phase 115	00	0.40	120	170	1450	0.5				
(TP)	4IK25GN-CW2J	4IK25GN-CW2TJ	25	Single-Phase 200	50	0.26	120	205	1200	2.0				
<u> </u>	(4IK25A-CW2J)	(4IK25A-CW2TJ)	25	Sillyle-Filase 200	60	0.20	120	170	1450	2.0				
				Single-Phase 220	50	0.27	110	205	1200					
(TP)	4IK25GN-CW2E	4IK25GN-CW2TE	25	Siligic-i flase 220	60	0.23	110	170	1450	1.5				
W.	(4IK25A-CW2E)	(4IK25A-CW2TE)	20	Single-Phase 230	50	0.27	120	205	1200	1.5				
				Siligic-i flase 250	60	0.23	120	170	1450					
				Three-Phase 200	50	0.23	240	190	1300					
(TP)	4IK25GN-SW2	4IK25GN-SW2T	25	111100 1 11030 200	60	0.21	160	160	1550	_				
•	(4IK25A-SW2)	(4IK25A-SW2T)	20	Three-Phase 220	60	0.21	160	160	1600					
				Three-Phase 230	60	0.22	160	160	1600					
TP	_	4IK25GN-UT4* (4IK25A-UT4*)	25	Three-Phase 400	50	0.12	240	190	1300	_				

<sup>●</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(P): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

## Product Line

## ● Motor (RoHS)

Tuno	Mo	odel
Type	Pinion Shaft Type	Round Shaft Type
	4IK25GN-AW2J	4IK25A-AW2J
	4IK25GN-AW2U	4IK25A-AW2U
Lead Wire	4IK25GN-CW2J	4IK25A-CW2J
	4IK25GN-CW2E	4IK25A-CW2E
	4IK25GN-SW2	4IK25A-SW2
	4IK25GN-AW2TJ	4IK25A-AW2TJ
	4IK25GN-AW2TU	4IK25A-AW2TU
Terminal Box	4IK25GN-CW2TJ	4IK25A-CW2TJ
Terrilliai Dux	4IK25GN-CW2TE	4IK25A-CW2TE
	4IK25GN-SW2T	4IK25A-SW2T
	4IK25GN-UT4	4IK25A-UT4

## Gearhead/Right-Angle Gearhead (Sold Separately) RoHS

Type	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	4GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	4GN10XS (Decima	al gearhead)
Right-Angle/ Hollow Shaft	4GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	4GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>■</sup> Enter the gear ratio in the box (□) within the model name.

<sup>\*</sup> Conforms to EN/IEC standards only. Bears the CE Marking.

## Gearmotor – Torque Table

- Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio. The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.
- To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 8 N·m. When a gearhead of 1/25~1/36 is connected, the value for permissible torque is 6 N·m.

√30 HZ																				UIII	r = 14 111
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4IK25GN-AW2 J 4IK25GN-CW2 J 4IK25GN-CW2 E	<b>dGN</b> □S	0.50	0.60	0.83	1.0	1.2	1.5	2.1	2.5	3.0	3.7	4.5	5.4	6.8	8	8	8	8	8	8	8
4IK25GN-SW2□ 4IK25GN-UT4	/ 4GN□S	0.46	0.55	0.77	0.92	1.2	1.4	1.9	2.3	2.8	3.5	4.2	5.0	6.3	7.5	8	8	8	8	8	8
<b>♦60 Hz</b>																				Uni	it = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/	Goar Patio	2	2.4	_	_	7.5	0	12.5	15	10	25	20	24	50	40	75	00	100	120	150	100

Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4IK25GN-AW2_J 4IK25GN-AW2_U 4IK25GN-CW2_J 4IK25GN-CW2_E	dGN□S	0.41	0.50	0.69	0.83	1.0	1.2	1.7	2.1	2.5	3.1	3.7	4.5	5.6	6.7	8	8	8	8	8	8
4IK25GN-SW2□	/ 4GN□S	0.39	0.47	0.65	0.78	0.97	1.2	1.6	1.9	2.3	2.9	3.5	4.2	5.3	6.3	7.9	8	8	8	8	8

22.5

## Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

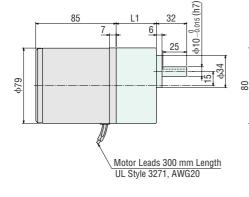
## Permissible Load Inertia J for Gearhead

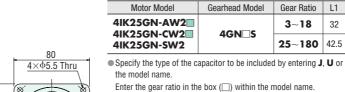
→ Page 107

## Dimensions (Unit = mm)

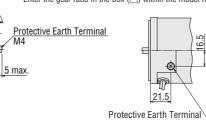
Mounting screws are included with gearheads.





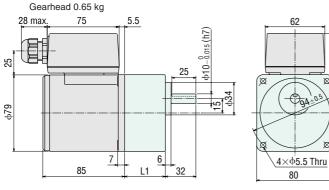


lacksquare Specify the type of the capacitor to be included by entering lacksquare, lacksquare or lacksquare in the box (lacksquare) within



Detail Drawing of Protective Earth Terminal

Mass: Motor 1.7 kg



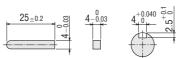
Motor Model	Gearhead Model	Gear Ratio	L1
4IK25GN-AW2T■ 4IK25GN-CW2T■	4GN⊟S	3~18	32
4IK25GN-SW2T 4IK25GN-UT4	4GN⊔5	<b>25</b> ~180	42.5

Specify the type of the capacitor to be included by entering J, U or E in the box (
 within the model name.

Enter the gear ratio in the box ( ) within the model name.

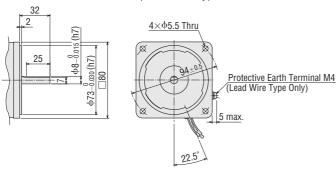
## 

(The key is included with the gearhead)



## ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

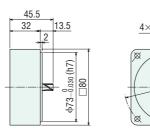


#### 

Can be connected to **GN** pinion shaft type. **4GN10XS** 

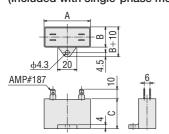
Mass: 0.4 kg

43



# 4×Φ5.5 Thru

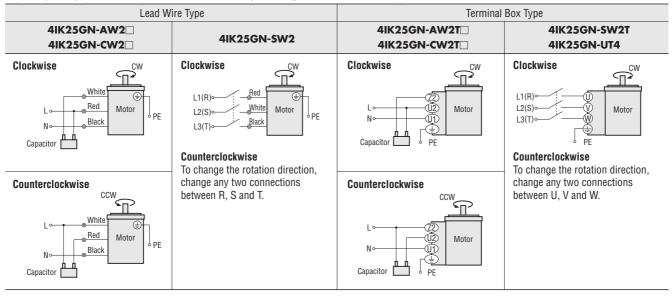
## 



Upper Model Name Lower Model Name	Capacitor Model	Α	В	С	Mass (g)	Capacitor Cap	
Lead Wire Type	Terminal Box Type						
4IK25GN-AW2J (4IK25A-AW2J)	4IK25GN-AW2TJ (4IK25A-AW2TJ)	CH80CFAUL2	48	21	31	45	
4IK25GN-AW2U (4IK25A-AW2U)			48	19	29	40	Included
4IK25GN-CW2J (4IK25A-CW2J)	4IK25GN-CW2TJ (4IK25A-CW2TJ)	CH20BFAUL	48	19	29	35	iliciuded
4IK25GN-CW2E (4IK25A-CW2E)	4IK25GN-CW2TE (4IK25A-CW2TE)	CH15BFAUL	38	21	31	35	

## Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- •Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (□) within the model name.



PE: Protective Earth

Note:

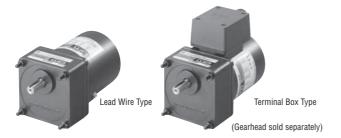
Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

(RoHS)
Induction Motors

40 W

Frame Size: **□90** mm



Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## ■Specifications - Continuous Rating RoHS



-			• -						
Mode Upper Model Name: Lower Model Name ()	Pinion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	A	mN∙m	mN∙m	r/min	μF
5IK40GN-AW2J	5IK40GN-AW2TJ	40	40 Single-Phase 100		0.76	200	315	1250	11
(5IK40A-AW2J)	(5IK40A-AW2TJ)	40			0.74	200	260	1500	11
5IK40GN-AW2U	5IK40GN-AW2TU	40	Single-Phase 110	00	0.68	000	000	1500	0.0
(5IK40A-AW2U)	(5IK40A-AW2TU)	40	Single-Phase 115	60	0.67	200	260	1500	9.0
5IK40GN-CW2J	5IK40GN-CW2TJ	40	40 Single-Phase 200		0.39	000	315	1250	0.0
(5IK40A-CW2J)	(5IK40A-CW2TJ)	40	Single-Phase 200	60	0.40	200	260	1500	3.0
			Cinala Dhana 000	50	0.39		315	1250	
5IK40GN-CW2E	5IK40GN-CW2TE	40	Single-Phase 220	60	0.35	200	260	1500	2.3
(51K40A-CW2E)	(5IK40A-CW2TE)	40	Cinala Dhana 000	50	0.39	200	300	1300	2.3
			Single-Phase 230	60	0.34		260	1500	
			Thurs Dhass 000	50	0.32	400	300	1300	
5IK40GN-SW2	5IK40GN-SW2T	40	Three-Phase 200	60	0.30	260	260	1550	
(5IK40A-SW2)	(5IK40A-SW2T)	40	Three-Phase 220	60	0.30	260	260	1600	_
			Three-Phase 230	60	0.31	260	260	1600	
<b>TP</b> –	5IK40GN-UT4* (5IK40A-UT4*)	40	Three-Phase 400	50	0.16	500	315	1250	-

<sup>•</sup> The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

#### Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

**P**: Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

## **Product Line**

## ● Motor (RoHS)

Type	Mo	odel
туре	Pinion Shaft Type	Round Shaft Type
	5IK40GN-AW2J	5IK40A-AW2J
	5IK40GN-AW2U	5IK40A-AW2U
Lead Wire	5IK40GN-CW2J	5IK40A-CW2J
	5IK40GN-CW2E	5IK40A-CW2E
	5IK40GN-SW2	5IK40A-SW2
	5IK40GN-AW2TJ	5IK40A-AW2TJ
	5IK40GN-AW2TU	5IK40A-AW2TU
Torminal Day	5IK40GN-CW2TJ	5IK40A-CW2TJ
Terminal Box	5IK40GN-CW2TE	5IK40A-CW2TE
	5IK40GN-SW2T	5IK40A-SW2T
	5IK40GN-UT4	5IK40A-UT4

#### Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Type	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	5GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GN10XS (Decima	al gearhead)
Right-Angle/ Hollow Shaft	5GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

 $<sup>\</sup>bullet$  Enter the gear ratio in the box (  $\square$  ) within the model name.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

 $<sup>\</sup>ensuremath{\bigstar}$  Conforms to EN/IEC standards only. Bears the CE Marking.

## ■Gearmotor - Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.
- The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 10 N·m.

<>50 Hz	50 Hz Unit = N·m																				
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK40GN-AW2J 5IK40GN-CW2J 5IK40GN-CW2E (Single-phase 220 VAC)	5GN□S	0.77	0.92	1.3	1.5	1.9	2.3	3.2	3.8	4.6	5.7	6.9	8.3	10	10	10	10	10	10	10	10
5IK40GN-CW2 E (Single-phase 230 VAC) 5IK40GN-SW2	5GN□S	0.73	0.87	1.2	1.5	1.8	2.2	3.0	3.6	4.4	5.5	6.6	7.9	9.9	10	10	10	10	10	10	10
5IK40GN-UT4	/ 5GN□S	0.77	0.92	1.3	1.5	1.9	2.3	3.2	3.8	4.6	5.7	6.9	8.3	10	10	10	10	10	10	10	10

<b>♦60 Hz</b>	>60 Hz Unit = N·m										t = N·m										
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK40GN-AW2_J 5IK40GN-AW2_U 5IK40GN-CW2_J 5IK40GN-CW2_E 5IK40GN-SW2_	5GN□S	0.63	0.76	1.1	1.3	1.6	1.9	2.6	3.2	3.8	4.7	5.7	6.8	8.6	10	10	10	10	10	10	10

## ■Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

→ Page 107

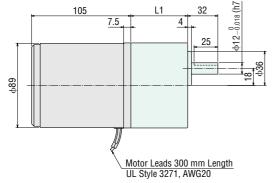
## Dimensions (Unit = mm)

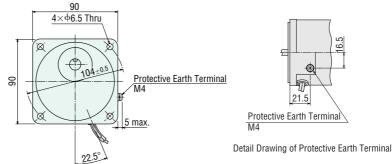
Mounting screws are included with gearheads.

Motor Model	Gearhead Model	Gear Ratio	L1
5IK40GN-AW2	5 CN□5	3~18	42
5IK40GN-CW2	5GN_S	<b>25</b> ~180	60

 $<sup>\</sup>bullet$  Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box ( ) within the model name.

Enter the gear ratio in the box ( $\square$ ) within the model name.



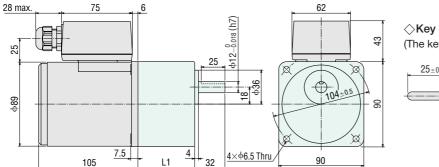


Mass: Motor 2.6 kg Gearhead 1.5 kg

Motor Model	Gearhead Model	Gear Ratio	L1
5IK40GN-AW2T 5IK40GN-CW2T	5GN⊟S	3~18	42
5IK40GN-SW2T 5IK40GN-UT4	3GN_3	<b>25</b> ~180	60

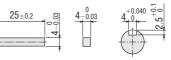
ullet Specify the type of the capacitor to be included by entering  ${f J}, {f U}$  or  ${f E}$  in the box ( ${f lue{f lue{f lue{f lue{f b}}}}}$ ) within the model name

Enter the gear ratio in the box  $(\Box)$  within the model name.



## 

(The key is included with the gearhead)



 $\bullet$  Use cable with a diameter of  $\varphi 6 \sim \varphi 12$  mm.

## ♦ Shaft Section of Round Shaft Type

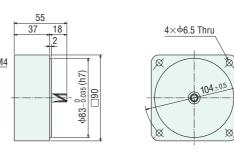
The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

# $4 \times \Phi 6.5$ Thru .035 (h7) <del>-</del>010-Protective Earth Terminal M4 (Lead Wire Type Only) 5 <u>max</u>. 22.5°

#### 

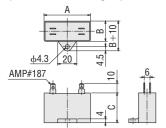
Can be connected to **GN** pinion shaft type. **5GN10XS** 

Mass: 0.6 kg



## 

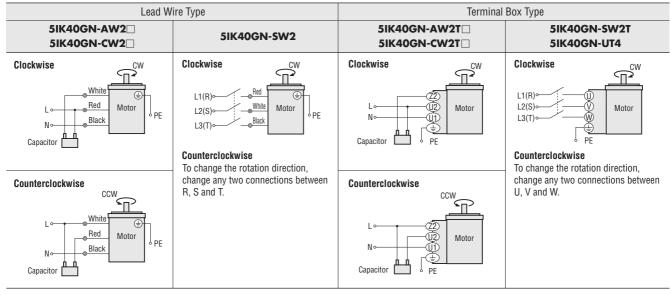
(Included with single-phase motors)



Upper Model Name Lower Model Name Lead Wire Type	Capacitor Model	А	В	С	Mass (g)	Capacitor Cap	
	Terminal Box Type						
5IK40GN-AW2J (5IK40A-AW2J)	5IK40GN-AW2TJ (5IK40A-AW2TJ)	CH110CFAUL2	58	21	31	50	
5IK40GN-AW2U (5IK40A-AW2U)	5IK40GN-AW2TU (5IK40A-AW2TU)	CH90CFAUL2	48	22.5	31.5	45	Included
5IK40GN-CW2J (5IK40A-CW2J)	5IK40GN-CW2TJ (5IK40A-CW2TJ)	CH30BFAUL	58	21	31	50	Iliciadea
5IK40GN-CW2E (5IK40A-CW2E)	5IK40GN-CW2TE (5IK40A-CW2TE)	CH23BFAUL	48	21	31	40	

## Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

Induction Motors

# **60 W**

Frame Size: 

□90 mm





(Gearhead sold separately)

Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## ■Specifications – Continuous Rating (RoHS)

c <b>FL</b> us	<b>(W</b> )	C	(
----------------	-------------	---	---

Mode Upper Model Name: F Lower Model Name ():	Pinion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	w	VAC	Hz	A	mN∙m	mN•m	r/min	μF
5IK60GE-AW2J	5IK60GE-AW2TJ	60	Single-Phase 100	50	1.20	320	490	1200	20
(5IK60A-AW2J)	(5IK60A-AW2TJ)	00	Siligie-Pliase 100	60	1.19	320	405	1450	20
5IK60GE-AW2U	5IK60GE-AW2TU	60	Single-Phase 110	60	1.09	320	405	1450	18
(5IK60A-AW2U)	(5IK60A-AW2TU)	00	Single-Phase 115	00	1.10	320	405	1450	10
5IK60GE-CW2J	5IK60GE-CW2TJ	60	Cingle Phase 200	50	0.57	320	490	1200	5.0
(5IK60A-CW2J)	(5IK60A-CW2TJ)	00	Single-Phase 200	60	0.65	320	405	1450	5.0
			Cingle Dhose 220	50	0.55		490	1200	
5IK60GE-CW2E	5IK60GE-CW2TE	60	Single-Phase 220	60	0.54	320	405	1450	4.0
(5IK60A-CW2E)	(5IK60A-CW2TE)	00	Cinalo Dhoos 220	50	0.57	320	490	1200	4.0
			Single-Phase 230	60	0.54		405	1450	
			Three-Phase 200	50	0.50	600	450	1300	
5IK60GE-SW2	5IK60GE-SW2T	60	Tillee-Filase 200	60	0.43	500	380	1550	
(5IK60A-SW2)	(5IK60A-SW2T)	00	Three-Phase 220	60	0.45	500	380	1600	_
			Three-Phase 230	60	0.46	500	380	1600	
<b>TP</b> –	5IK60GE-UT4F* (5IK60A-UT4F*)	60	Three-Phase 400	50	0.25	550	470	1250	-

<sup>The</sup> **J**, **U** and **E** at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

#### Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(TP): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

## Product Line

#### ● Motor (RoHS)

Tuno	M	odel					
Type	Pinion Shaft Type	Round Shaft Type					
	5IK60GE-AW2J	5IK60A-AW2J					
	5IK60GE-AW2U	5IK60A-AW2U					
Lead Wire	5IK60GE-CW2J	5IK60A-CW2J					
	5IK60GE-CW2E	5IK60A-CW2E					
	5IK60GE-SW2	5IK60A-SW2					
	5IK60GE-AW2TJ	5IK60A-AW2TJ					
	5IK60GE-AW2TU	5IK60A-AW2TU					
Terminal Box	5IK60GE-CW2TJ	5IK60A-CW2TJ					
Terrilliai box	5IK60GE-CW2TE	5IK60A-CW2TE					
	5IK60GE-SW2T	5IK60A-SW2T					
	5IK60GE-UT4F	5IK60A-UT4F					

## • Gearhead/Right-Angle Gearhead (Sold Separately) RoHS

Туре	Gearhead Model	Gear Ratio
Long Life/ Parallel Shaft	5GE□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE10XS (Decima	l gearhead)
Right-Angle/ Hollow Shaft	5GE□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>■</sup> Enter the gear ratio in the box (□) within the model name.

<sup>\*</sup>Conforms to EN/IEC standards only. Bears the CE Marking.

## ■Gearmotor – Torque Table

- •Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.
- The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

<>50 Hz																				Uni	t = N·m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK60GE-AW2J 5IK60GE-CW2J 5IK60GE-CW2E	5GE□S	1.2	1.4	2.0	2.4	3.0	3.6	4.5	5.4	6.4	8.1	9.7	11.6	16.2	19.4	20	20	20	20	20	20
5IK60GE-SW2■	5GE□S	1.1	1.3	1.8	2.2	2.7	3.3	4.1	4.9	5.9	7.4	8.9	10.7	14.9	17.8	19.9	20	20	20	20	20
5IK60GE-UT4F	5GE□S	1.1	1.4	1.9	2.3	2.9	3.4	4.3	5.1	6.2	7.8	9.3	11	16	19	20	20	20	20	20	20

<b>♦60 Hz</b>																				Uni	t = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK60GE-AW2_J 5IK60GE-AW2_U 5IK60GE-CW2_J 5IK60GE-CW2_E	<b>5GE</b> □S	0.98	1.2	1.6	2.0	2.5	3.0	3.7	4.4	5.3	6.7	8.0	9.6	13.4	16.0	17.9	20	20	20	20	20
5IK60GE-SW2■	/ 5GE□S	0.92	1.1	1.5	1.8	2.3	2.8	3.5	4.2	5.0	6.3	7.5	9.0	12.5	15.0	16.8	20	20	20	20	20

## ■Permissible Overhung Load and Permissible Thrust Load

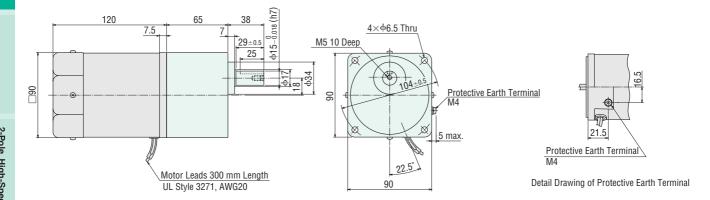
Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

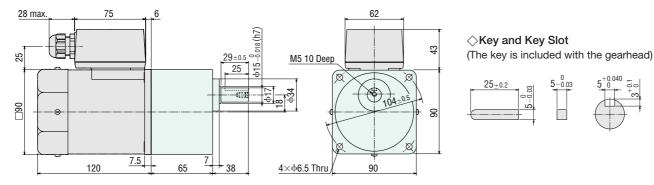
→ Page 107

## ■ Dimensions (Unit = mm)

Mounting screws are included with gearheads.



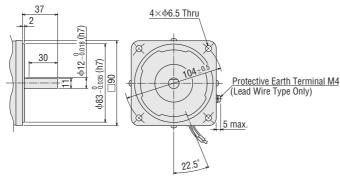
Mass: Motor 2.8 kg Gearhead 1.5 kg



• Use cable with a diameter of  $\phi 6 \sim \phi 12$  mm.

## ♦ Shaft Section of Round Shaft Type

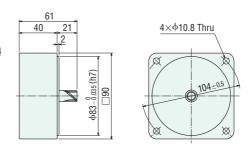
The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



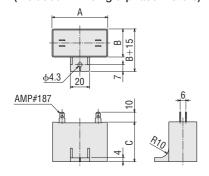
#### 

Can be connected to **GE** pinion shaft type. 5GE10XS

#### Mass: 0.6 kg



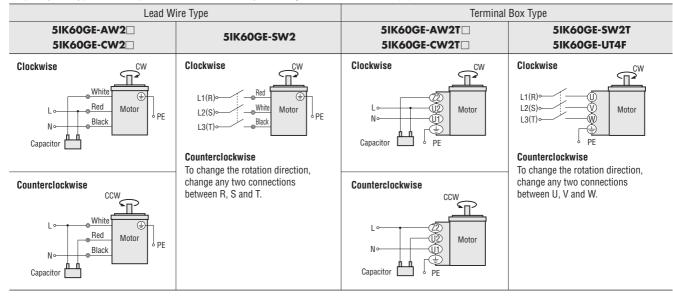
## (Included with single-phase motors)



Upper Model Name	odel e: Pinion Shaft Type (): Round Shaft Type	Capacitor Model	А	В	С	Mass (g)	Capacitor Cap
Lead Wire Type	Terminal Box Type						
5IK60GE-AW2J (5IK60A-AW2J)	5IK60GE-AW2TJ (5IK60A-AW2TJ)	CH200CFAUL2	58	29	41	95	
5IK60GE-AW2U (5IK60A-AW2U)	5IK60GE-AW2TU (5IK60A-AW2TU)	CH180CFAUL2	58	29	41	95	Included
5IK60GE-CW2J (5IK60A-CW2J)	5IK60GE-CW2TJ (5IK60A-CW2TJ)	CH50BFAUL	58	29	41	85	Included
5IK60GE-CW2E (5IK60A-CW2E)	5IK60GE-CW2TE (5IK60A-CW2TE)	CH40BFAUL	58	23.5	37	70	

## Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

#### Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

(RoHS)
Induction Motors

# 90 W

Frame Size: **□90** mm





Right-angle gearheads (hollow shaft or solid shaft) can be combined.

Right-Angle Gearheads → Page 108





## ■Specifications – Continuous Rating RoHS



Mode Upper Model Name: Lower Model Name ()	Pinion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	A	mN∙m	mN∙m	r/min	μF
5IK90GE-AW2J	5IK60GE-AW2TJ	90	Single-Phase 100	50	1.64	450	700	1250	28
(5IK90A-AW2J)	(5IK90A-AW2TJ)	90	Sillyle-Filase 100	60	1.67	430	585	1500	20
5IK90GE-AW2U	5IK90GE-AW2TU	00	Single-Phase 110	60	1.45	450	585	1500	20
(5IK90A-AW2U)	(5IK90A-AW2TU)	90	90 Single-Phase 115		1.44	450	363	1500	20
5IK90GE-CW2J	5IK90GE-CW2TJ	00	Cingle Dhose 200	50	0.80	450	730	1200	7.0
(5IK90A-CW2J)	(5IK90A-CW2TJ)	90	90 Single-Phase 200		0.93	450	605	1450	7.0
			Single-Phase 220		0.74		730	1200	
5IK90GE-CW2E	5IK90GE-CW2TE	90	Siligie-Pliase 220	60	0.82	450	605	1450	6.0
(51K90A-CW2E)	(5IK90A-CW2TE)	90	Cinala Dhana 000	50	0.76	450	730	1200	6.0
			Single-Phase 230	60	0.81		605	1450	
			Three Dhace 000	50	0.64	850	680	1300	
5IK90GE-SW2	5IK90GE-SW2T	00	Three-Phase 200	60	0.59	700	570	1550	
(5IK90A-SW2)	(5IK90A-SW2T)	90 sw2T)	Three-Phase 220	60	0.60	700	570	1600	_
			Three-Phase 230	60	0.61	700	570	1600	
<b>TP</b> –	5IK90GE-UT4F* (5IK90A-UT4F*)	90		50	0.35	850	700	1250	-

The **J**, **U** and **E** at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

#### Note

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(P): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

## Product Line

#### ● Motor (RoHS)

Tuno	Mo	del
Туре	Pinion Shaft Type	Round Shaft Type
	5IK90GE-AW2J	5IK90A-AW2J
	5IK90GE-AW2U	5IK90A-AW2U
Lead Wire	5IK90GE-CW2J	5IK90A-CW2J
	5IK90GE-CW2E	5IK90A-CW2E
	5IK90GE-SW2	5IK90A-SW2
	5IK90GE-AW2TJ	5IK90A-AW2TJ
	5IK90GE-AW2TU	5IK90A-AW2TU
Terminal Box	5IK90GE-CW2TJ	5IK90A-CW2TJ
Terriniai Dux	5IK90GE-CW2TE	5IK90A-CW2TE
	5IK90GE-SW2T	5IK90A-SW2T
	5IK90GE-UT4F	5IK90A-UT4F

## • Gearhead/Right-Angle Gearhead (Sold Separately) RoHS

Туре	Gearhead Model	Gear Ratio
Long Life/ Parallel Shaft	5GE□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE10XS (Decima	l gearhead)
Right-Angle/ Hollow Shaft	5GE□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

<sup>■</sup> Enter the gear ratio in the box (□) within the model name.

<sup>\*</sup>Conforms to EN/IEC standards only. Bears the CE Marking.

## Gearmotor – Torque Table

- Gearheads and decimal gearheads are sold separately.
- ●Enter the code that represents the terminal box type "T" in the box (□) within the model name.
- ■Enter the gear ratio in the box (□) within the model name.
- •A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.
- The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.
- The actual speed is 2 20% less than the displayed value, depending on the size of the load.
- ■To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK90GE-AW2_J	/ 5GE□S	1.7	2.0	2.8	3.4	4.3	5.1	6.4	7.7	9.2	11.6	13.9	16.6	20	20	20	20	20	20	20	20
5IK90GE-CW2J 5IK90GE-CW2E	/ 5GE□S	1.8	2.1	3.0	3.5	4.4	5.3	6.7	8.0	9.6	12.0	14.5	17.3	20	20	20	20	20	20	20	20
5IK90GE-SW2	/ 5GE□S	1.7	2.0	2.8	3.3	4.1	5.0	6.2	7.4	8.9	11.2	13.5	16.2	20	20	20	20	20	20	20	20
5IK90GE-UT4F	/ 5GE□S	1.7	2.0	2.8	3.4	4.3	5.1	6.4	7.7	9.2	12	14	17	20	20	20	20	20	20	20	20

<b>♦60 Hz</b>																				Uni	it = N·m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK90GE-AW2□J 5IK90GE-AW2□U	/ 5GE□S	1.4	1.7	2.4	2.8	3.6	4.3	5.3	6.4	7.7	9.7	11.6	13.9	19.3	20	20	20	20	20	20	20
5IK90GE-CW2□J 5IK90GE-CW2□E	/ 5GE□S	1.5	1.8	2.5	2.9	3.7	4.4	5.5	6.6	7.9	10.0	12.0	14.4	20	20	20	20	20	20	20	20
5IK90GE-SW2	/ 5GE□S	1.4	1.7	2.3	2.8	3.5	4.2	5.2	6.2	7.5	9.4	11.3	13.5	18.8	20	20	20	20	20	20	20

## Permissible Overhung Load and Permissible Thrust Load

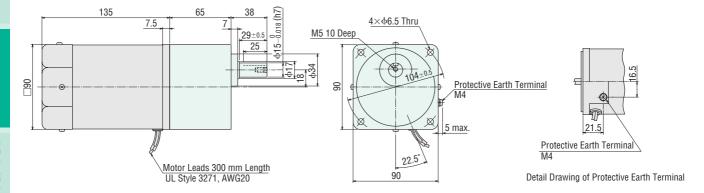
Motor (Round shaft type) → Page 107 Gearhead → Page 107

## Permissible Load Inertia J for Gearhead

→ Page 107

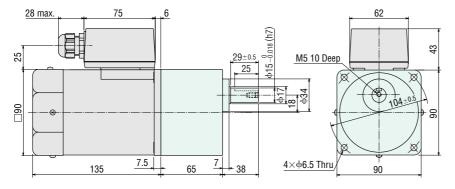
## ■ Dimensions (Unit = mm)

Mounting screws are included with gearheads.



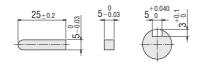
#### ♦ Terminal Box Type ②

Mass: Motor 3.3 kg Gearhead 1.5 kg



## 

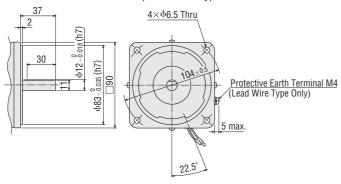
(The key is included with the gearhead)



• Use cable with a diameter of  $\phi 6 \sim \phi 12$  mm.

## ♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

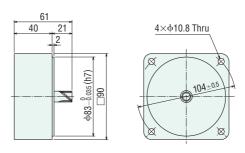


#### 

Can be connected to **GE** pinion shaft type.

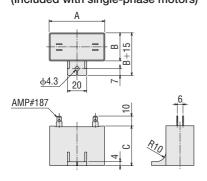
#### 5GE10XS

Mass: 0.6 kg



#### 

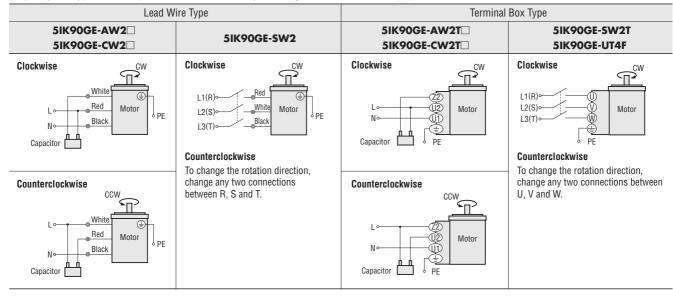
(Included with single-phase motors)



Upper Model Name	odel e: Pinion Shaft Type ( ): Round Shaft Type Terminal Box Type	Capacitor Model	А	В	С	Mass (g)	Capacitor Cap
5IK90GE-AW2J (5IK90A-AW2J)	5IK90GE-AW2TJ (5IK90A-AW2TJ)	CH280CFAUL2	58	35	50	140	
5IK90GE-AW2U (5IK90A-AW2U)	5IK90GE-AW2TU (5IK90A-AW2TU)	CH200CFAUL2	58	29	41	95	Included
5IK90GE-CW2J (5IK90A-CW2J)	5IK90GE-CW2TJ (5IK90A-CW2TJ)	CH70BFAUL	58	35	50	130	iliciuded
5IK90GE-CW2E (5IK90A-CW2E)	5IK90GE-CW2TE (5IK90A-CW2TE)	CH60BFAUL	58	29	41	85	

## ■Connection Diagrams

- The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.
- Connection diagrams are also valid for the equivalent round shaft type.
- Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

## RoHS RoHS-Compliant

## **Brake Pack for Standard AC Motors**

# **SB50W**

**AU**us **E**E

The **SB50W** provides instantaneous stop, forward/reverse operation, electromagnetic brake control and thermal protector open detection functions integrated into one unit. These brake packs can sense when the thermal protector is opened, further ensuring the safety of your equipment.



#### Features

#### Four Functions in One Integrated Unit

The **\$B50W** provides instantaneous stop, forward/reverse operation, electromagnetic brake control and thermal protector open detection functions\*.

\*Thermal protector open detection function

(Available only when combined with a motor having a built-in thermal protector) When the motor's thermal protector (overheat protection device) is activated, the **SB50W** outputs an alarm signal and automatically cuts the power supply to the motor. The motor will not restart by itself, even after the temperature drops and the thermal protector recovers, until the power is cycled. Possible to reset the alarm through external signals.

#### Wide Voltage Range of 100 to 230 VAC

The **\$B50W** covers a single-phase voltage range of 100 to 230 VAC  $\pm 10\%$ , 50/60 Hz, accommodating all of the world's key voltage specifications.

#### Conforms to Safety Standards

This is the world first brake pack which conforms to safety standards. The CE marking is used in accordance with the EMC directives and low voltage directives.

#### Supports Motors with 1 to 90 W Output

The **SB50W** can be used with induction, reversible, electromagnetic brake and watertight, dust-resistant motors with an output range of 1 to 90 W.

#### Switchable Sink/Source Logic

Select the sink mode or source mode for the input/output circuit. You can change the setting at any time.

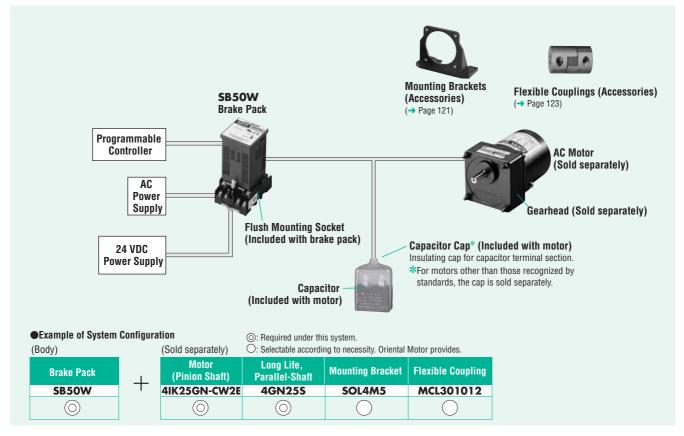
## Safety Standards and CE Marking

Standards	Certification Body	Standards File No.	CE Marking
UL 508	UL	E91291	Low Voltage Directives
CSA C22.2 No.14	UL	E91291	
EN 50178 EN 60950-1	Conform to EN Standards		EMC Directives

<sup>•</sup> The EMC value changes according to the wiring and layout. Therefore, the final EMC level must be checked with the brake pack incorporated in the user's equipment.

**M**us 66

## System Configuration



<sup>•</sup> The system configuration shown above is an example. Other configurations are available.

## Specifications (RoHS)

Mo	del	Power Supply Voltage	Frequency	Applicable Motor Output Voltage	Functions	Power Source for Control	Input Signals	Output Signals	Braking Current Duration
SB5	ow	Single-phase 100-230 VAC ±10%		1 W∼90 W	Instantaneous stop Forward/reverse operation Electromagnetic brake control (Electromagnetic brake motors) Thermal protector open detection (Alarm output) Sink/Source logic switch		CW, CCW, FREE/ALARM-RESET Input specifications Photocoupler input Input impedance 4.7 k $\Omega$ 24 VDC $\pm 10\%$	ALARM  Output specifications Open collector output External use conditions 26.4 VDC max. 10 mA min.	Approximately 0.2~0.4 seconds

## General Specifications

Item	Specifications		
Insulation Resistance			
Dielectric Strength	Sufficient to withstand 3.0 kV at 50 Hz or 60 Hz applied between the power supply input terminal and the signal input terminal for 1 minute after rated motor operation under normal ambient temperature and humidity.		
Ambient Temperature $0^{\circ}\text{C} \sim +40^{\circ}\text{C}$ (nonfreezing)			
Ambient Humidity	85% or less (noncondensing)		
Degree of Protection	IP10		

## Applicable Products

<sup>\*</sup> Except for 2-pole type

## Braking Current

When a motor is stopped suddenly, a large half-wave rectified current flows through the motor for approximately 0.2 to 0.4 seconds. When connecting a circuit breaker, fuse or transformer, refer to the table below for the braking current (peak value) and select its current capacity.

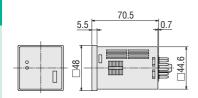
Motor Output Power	Braking Current [A] (Peak Value)			
Wotor Output Fower	100/110/115 VAC	200/220/230 VAC		
1 W	1.0	0.3*		
6 W	1.5	1.0		
15 W	4.5	2.5		
25 W	7.5	4.0		
40 W	12	7.0		
60 W	18	8.5		
90 W	26	17		

<sup>\*</sup>Can be used only for 200 VAC.

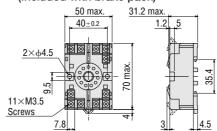
## Dimensions (Unit = mm)

## **♦SB50W**

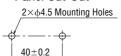
Mass: 0.1 kg



## Flush Mounting Socket (Included with brake pack)

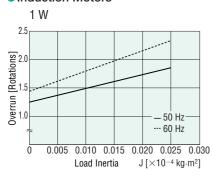


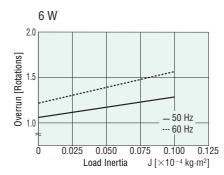
## Flush Mounting Socket Panel Cut-Out

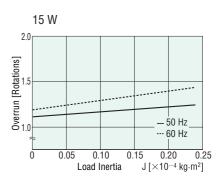


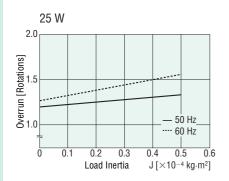
## ■ Braking Characteristics (Reference Values)

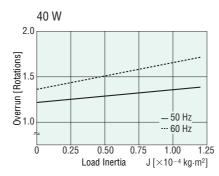
## Induction Motors

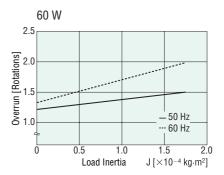


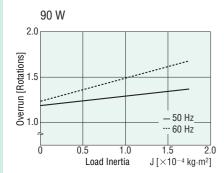




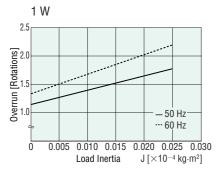


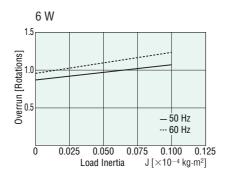


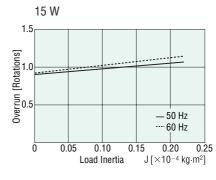


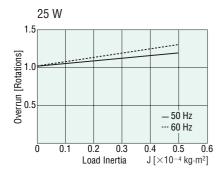


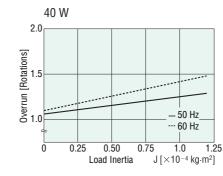
#### Reversible Motors

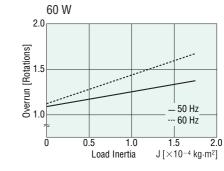


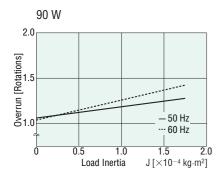




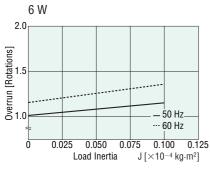


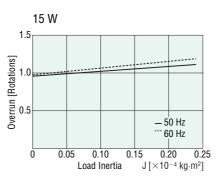


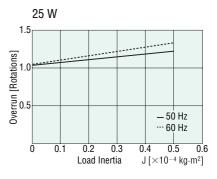


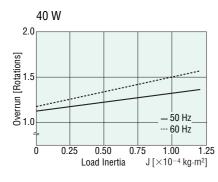


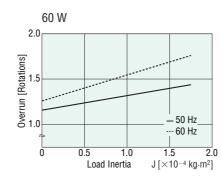
## Electromagnetic Brake Motors

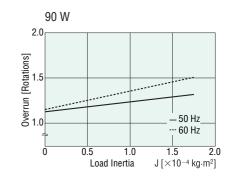












## Connection and Operation

#### Names and Functions of Brake Pack Parts

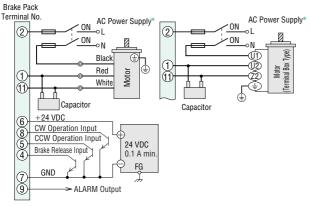


No.	Name	Factory Setting	Functions
1)	POWER Indicator (Green)	_	Lit when 24 VDC is supplied.
2	ALARM Indicator (Red)	-	Lit when the ALARM output is "OFF."
3	Motor Output Select Switch	60-90 W	Used to set the motor output.
4	SINK/SOURCE Select Switch	SINK	Used to switch between Sink/Source for the control signal output.

#### Connection Diagrams

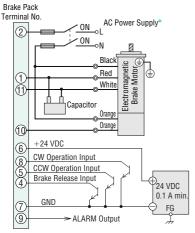
The wiring diagram is for when the SINK/SOURCE select switch is set to the "SINK" side.

## **♦**Induction Motors/Reversible Motors



\*Single-phase 100/110/115 VAC, single-phase 200/220/230 VAC

#### 



\*Single-phase 100/110/115 VAC, single-phase 200/220/230 VAC

## Terminal Arrangement for Flush Mounting Socket

Terminal No.	Signal Name	Description
1	Motor/Capacitor	Connect the motor and capacitor.
2	AC Power Input (L)	Single-phase 100 – 115 VAC Single-phase 200 – 230 VAC
3	NC	Not used. Leave this terminal unconnected.
<b>4</b> )*1	Brake Release Input*2	Not an instantaneous stop but a natural stop
(4)	ALARM-RESET Input	Reset ALARM Output.
(5)	CCW Operation Input*3	Motor runs in the CCW direction during "ON."
6	DC Power Input	+24 VDC input
7	GND	GND
8	CW Operation Input	Motor runs in the CCW direction during "ON."
9	ALARM Output	Turns "OFF" when the motor's thermal protector is "open."
10	Electromagnetic Brake*4	Connect to the electromagnetic brake.
11)	Motor/Capacitor	Connect the motor and capacitor.

- \*1 Functions as a brake release input during normal operation, and as an ALARM-RESET input when the ALARM output is OFF.
- \*2 Releases the electromagnetic brake for electromagnetic brake motors.
- \*3 Not used with an induction motor with four lead wires.
- \*4 Only for electromagnetic brake motors.

#### Notes:

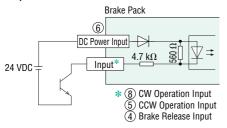
- The input-signal voltage is 24 VDC±10% and 0.1 A or more.
- $\blacksquare \ \, \text{Minimize the length of the motor cable and the input/output signal cable to reduce EMI.}$
- Use a cable of AWG18 (0.75 mm²) or more in diameter for the motor cable and power cable.
- Be sure to connect the GND terminal to GND (negative side) of the external controller, or the unit will not operate.

#### ●I/O Signal Circuit

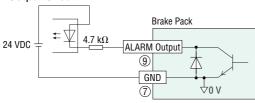
The I/O signal circuit can be switched between the sink mode and source mode using the sink/source select switch on the brake pack. The factory setting is the sink mode.

#### 

#### •Input Circuit

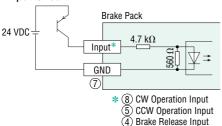


#### Output Circuit

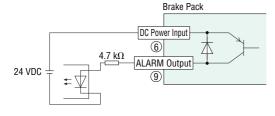


## 

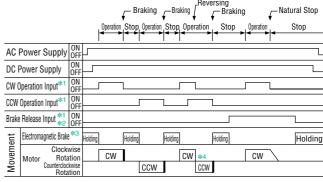
## •Input Circuit



## Output Circuit



#### Timing Chart



- \*1 Turn on CW operation input, CCW operation input, and brake release input after turning on AC power.
  - The motor does not operate if they are input ahead of AC power.

The ALARM indicator will light and ALARM output will switch to "OFF."

- \*2 The brake release input becomes ALARM-RESET input when the ALARM output is OFF.
- \*3 Only for electromagnetic brake motors.
- \*4 The induction motor will not accommodate instantaneous forward/reverse switching.

## 

Turning the CW operation signal to "ON" causes the motor's output shaft to turn in the CW direction. Turning it to "OFF" triggers an instantaneous stop.

#### **♦** CCW Operation Input

Turning the CCW operation signal to "ON" causes the motor's output shaft to turn in the CCW direction. Turning it to "OFF" triggers an instantaneous stop.

If both the CW and CCW operation signals are simultaneously turned to "ON," the CW operation signal will take priority. Therefore, the wiring must be changed with an induction motor having four lead wires.

#### ♦ Brake Release Input [ALARM-RESET Input]

Functions as a brake release input during normal operation, and as an ALARM-RESET input when the ALARM output is OFF.

## •When normal: [Brake Release Input]

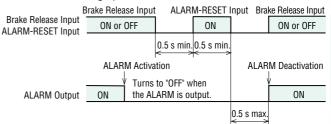
Turning the brake release signal to "ON" disables both the electronic brake and electromagnetic brake. When the CW and CCW operation signals are turned to "OFF," the motor operates via inertial force before coming to a natural stop. When the motor is stationary, the electromagnetic brake is not activated, so the motor's output shaft can be moved freely.

Turning the brake release signal to "OFF" (or leaving the signal unconnected) and turning both CW and CCW operation signals to "OFF" will activate the electronic brake and electromagnetic brake, bringing the motor to an instantaneous stop. Once the motor stops, the electronic brake will release automatically. However, the electromagnetic brake will continue to operate and hold the load.

#### •When ALARM output is OFF: [ALARM-RESET Input]

When ALARM output is turned OFF, turn all input signals "OFF" and input 0.5 seconds or more for ALARM-RESET input.

Wait at least 0.5 seconds after turning the ALARM-RESET input OFF before restarting operation.



It is also possible to deactivate the alarm by turning off the power and turning it on again. Turn off the DC or AC power, and turn all input signals "OFF" before turning on the power again.

#### 

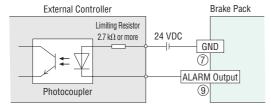
Since the **\$B50W** ALARM output function detects the operations of the thermal protector, the current flowing in the motor is monitored. Operation occurs under the following conditions:

- •When the thermal protector built-in to the motor is opened
- •When there is improper connection/disconnection of the power supply cable and motor cable
- •When the input signal is turned "ON" before the AC power is turned on
- •When the AC power is turned off while the motor is in operation or while it is stopped

In the above conditions, state of the **SB50W** ALARM output is "OFF," the ALARM indicator lamp (red) on the panel lights up, and power supply to the motor is stopped.

With electromagnetic brake motors, the brake is activated in order to hold the load in position.

\*When the DC power is turned on, the alarm indication lamp lights up instantaneously, but this is not an abnormality.



Use a power source of 26.4 VDC or less, and limit the output current to 10 mA or less.

## Operating/Braking Repetition Cycle

The repeated operation and braking of a motor will cause about a temperature increase in the motor and brake pack, thereby limiting the continuous operating time.

Observe the repetition cycle given in the table below for the operation and braking of the motor. The motor may generate heat depending on the conditions in which it is driven. Ensure that the temperature of the motor case does not exceed 90°C.

Motor Output Power	Repetition Cycle	
1 W~25 W	2 seconds or more	
40 W~90 W	4 seconds or more	

(A repetition cycle of two seconds represents operation for one second and stopping for one second.)

# **Accessories**

## ■ Motor/Gearhead Mounting Brackets (ROHS)

Mounting Brackets for attaching and securing a motor and gearhead. They are high-strength type, which can be used with high power motors/gearheads. These brackets come with tapped holes. To mount the motor and gearhead, simply fasten with the screws provided to the gearhead. To mount the motor alone, mounting screws must be provided separately.

Please note that these mounting brackets cannot be used with the following products.

• Right-angle gearheads (**RH** type, **RA** type)



## For Motor Frame Size: □42 mm

• Model: **SOLOM3** 

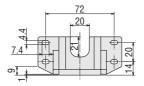
Mass: 85 g Material: Aluminum

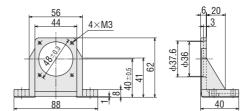
 $\Diamond$ Applicable Products

**OGN** Gearhead

Motor with the flame size of □42 mm

#### Dimensions (Unit = mm)





## For Motor Frame Size: ☐60 mm

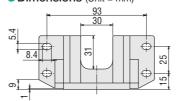
• Model: SOL2M4

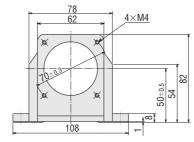
Mass: 135 g Material: Aluminum

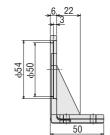
**2GN** Gearhead

Motor with the flame size of  $\square 60 \text{ mm}$ 

## • Dimensions (Unit = mm)







## ■For Motor Frame Size: 70 mm

## Model: SOL3M5

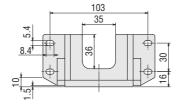
Mass: 175 g Material: Aluminum

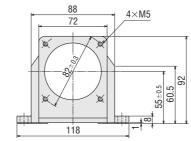
## $\Diamond$ Applicable Products

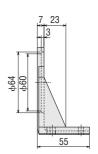
#### **3GN** Gearhead

Motor with the flame size of  $\Box 70 \text{ mm}$ 

● Dimensions (Unit = mm)







## ■For Motor Frame Size: 80 mm

## • Model: SOL4M5

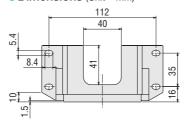
Mass: 210 g Material: Aluminum

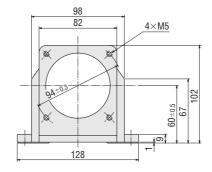
## 

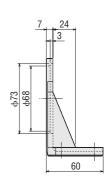
#### 4GN Gearhead

Motor with the flame size of □80 mm

#### ● Dimensions (Unit = mm)







## ■For Motor Frame Size: 90 mm

## • Model: SOL5M6

Mass: 270 g Material: Aluminum

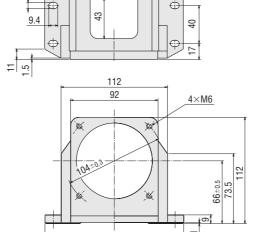
#### 

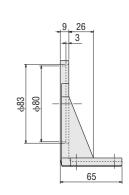
## 5GN Gearhead

**5GE** Gearhead

Motor with the flame size of  $\square 90 \text{ mm}$ 

## • Dimensions (Unit = mm)





## ■Capacitor Cap RoHS

Insulating cap for capacitor terminal section.

(Example of use)



Use a capacitor cap suitable for the external dimensions (A $\times$ B) of the capacitor.

Material: Polyvinyl chloride

Our capacitor caps are recognized by UL.

UL File No. E56078

## Flexible Couplings RoHS

These products are the clamping type couplings to connect between the shaft of motor/gearhead and the shaft of the equipment to be connected.

Once the motor and gearhead are determined, the coupling can be done.



**External Dimensions** 

 $A \times B$ 

(Unit = mm)

 $58 \times 35$ 

Model

CHC5835AUL

Ten capacitor caps are included in one bag. Order capacitor caps in a multiple of one bag. Applicable Capacitor

Model

CH400300A

#### Features

- Couplings come with shaft holes and have standardized combinations for different diameter shaft holes.
- Characteristics are the same for clockwise and counterclockwise rotation.
- Oil-resistant and electrically insulated.
- Aluminum alloy construction.
- •The shaft being driven is not damaged, since shafts are joined by clamping.
- Easy installation due to a separated hub and sleeve design.

Gearhead Model	Coupling Type
0GN□K	MCL20
2GN□S	MCL20 MCL30
3GN□S	MCL30
4GN□S	MCL30
4GN□RA	MCL40
5GN□S	MCL30
5GN□RA	MCL40
5GE□S	MCL40
5GE□RA	MCL55

st Type of coupling varies depending on condition of the load.

## ■CR Circuit for Surge Suppression (RoHS)

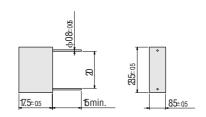
This product is used to protect the contacts of the relay and/ or switch used for controlling the reversal of direction and the electromagnetic brake.

• Model: **EPCR1201-2** 250 VAC (120 Ω, 0.1 μF)



## • Dimensions (Unit = mm)

Mass: 5 g



# **Oriental motor**

This product is manufactured at a plant certified with the international standards ISO 9001 (for quality assurance) and ISO 14001 (for systems of environmental management).

Specifications are subject to change without notice.

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